

Air Quality Forecasting in South African Urban Areas Using LSTM Models and SACAQM Data to Capture Temporal Dynamics and Patterns

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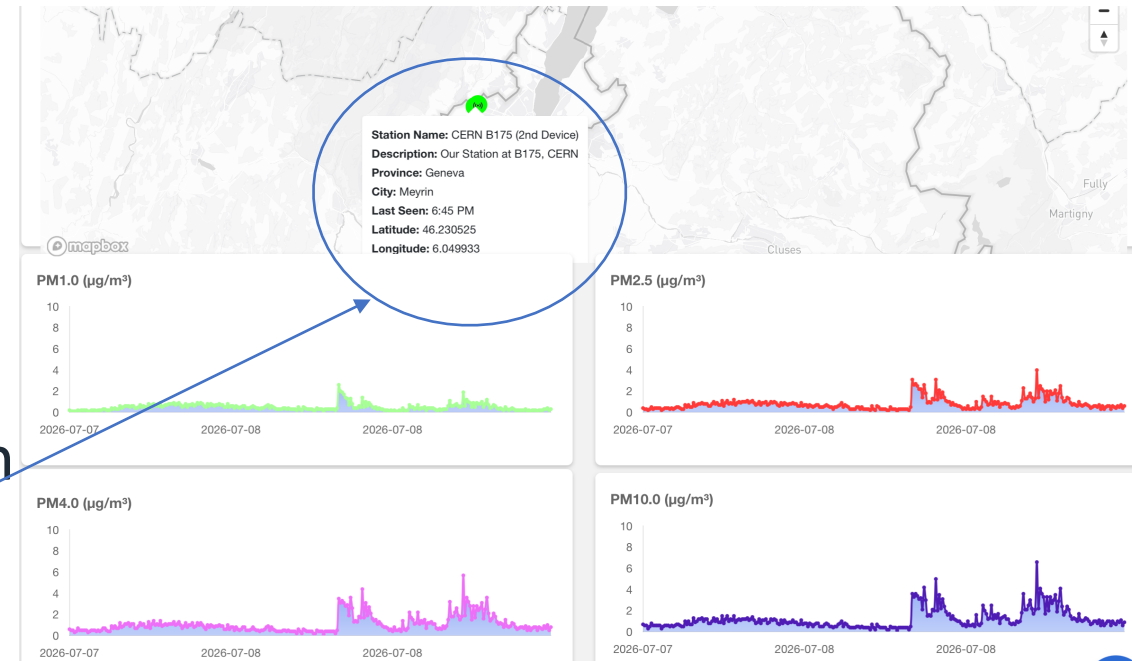
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Part 1 — Some Background on air quality monitoring

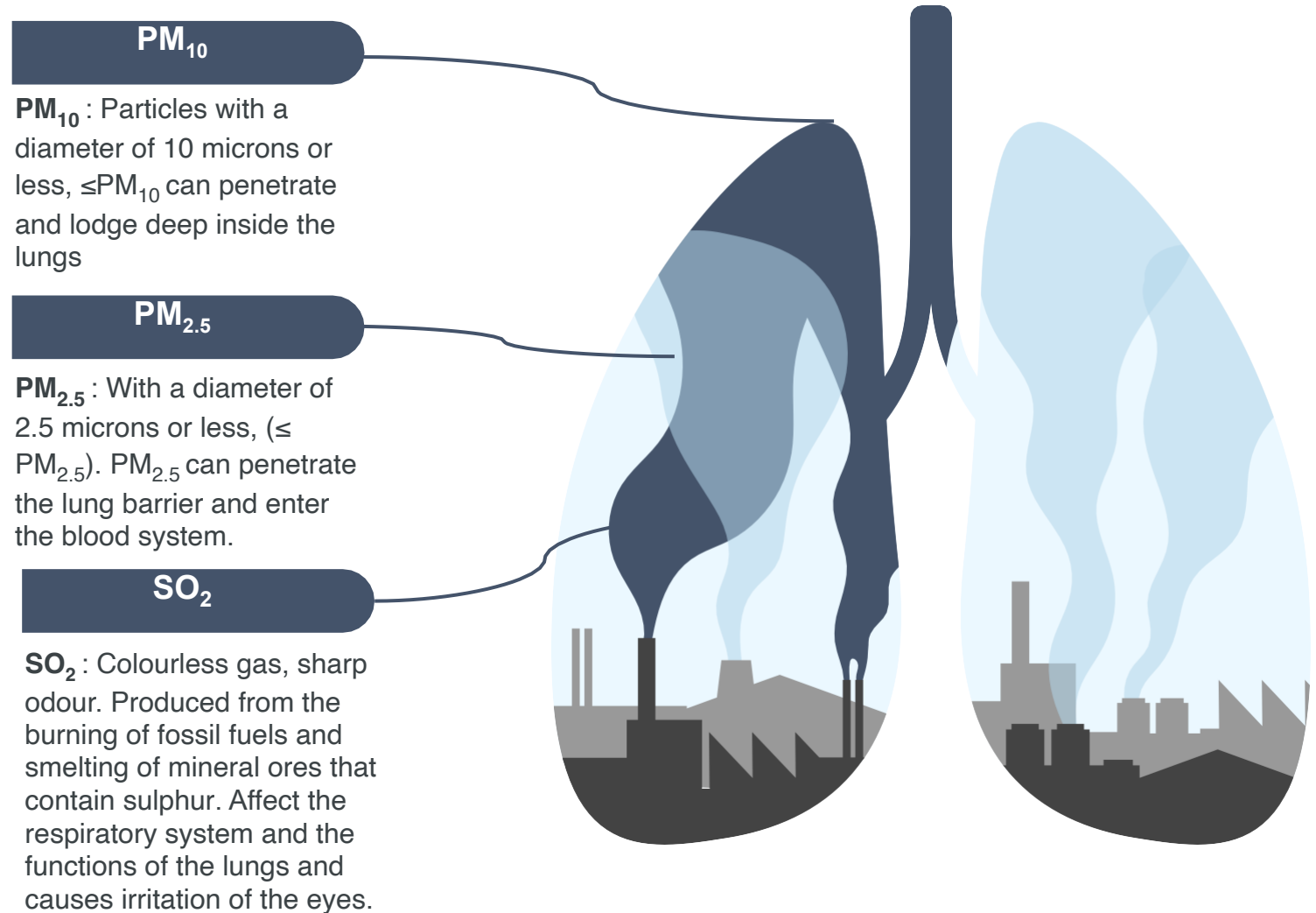
Why air quality monitoring matters

- 7 million people die from air pollution annually worldwide.
- This includes more than 1.7 million children deaths a year worldwide.
- In 2019, 99% of the world's population was found to breath air that exceeds the **World Health Organisation** limits.
- Moreover, air quality monitoring (temperature, humidity, radon, dust) matters in detector caverns for electronics reliability in research infrastructure such as the ATLAS at CERN.



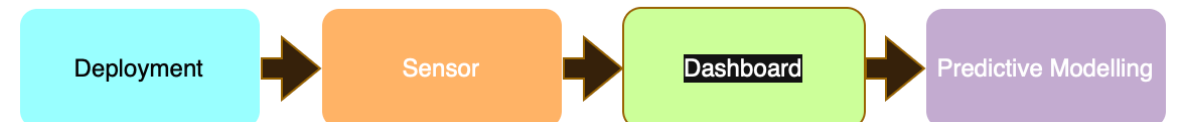
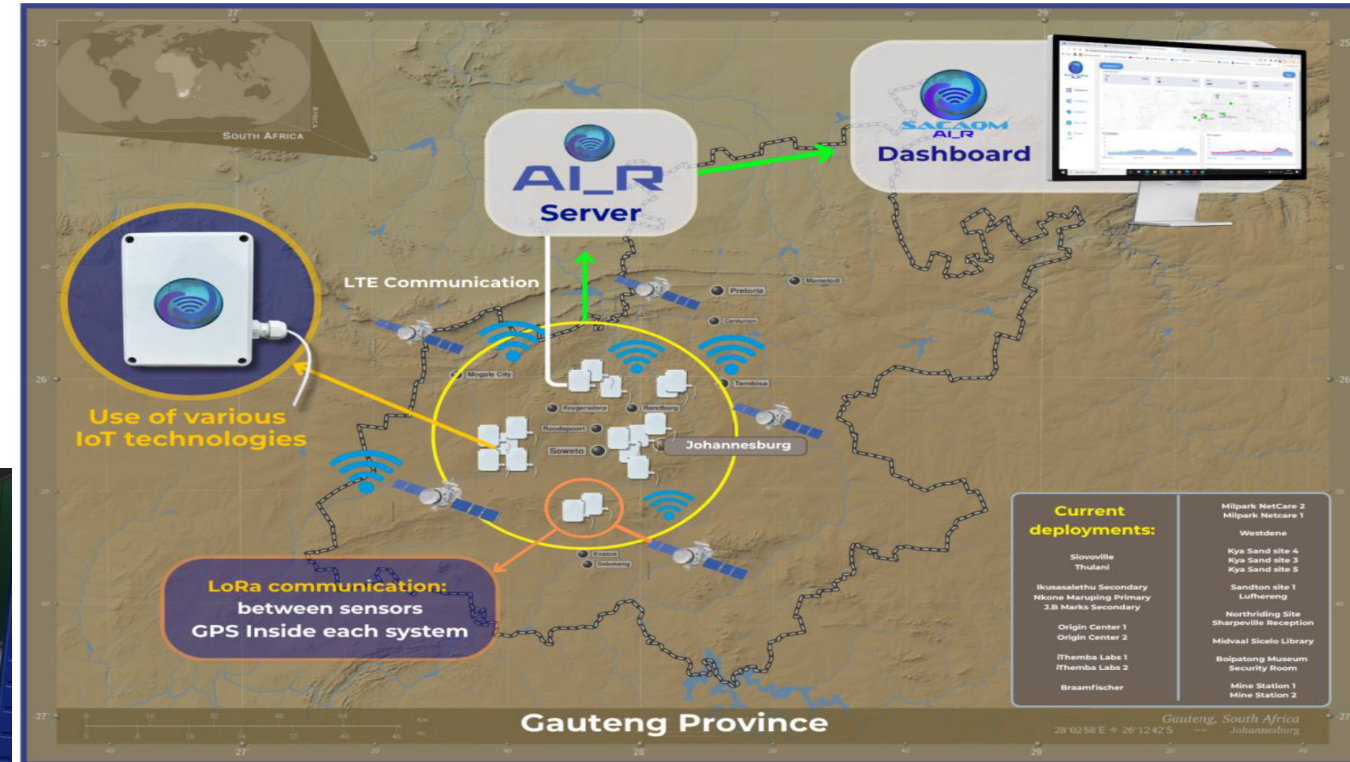
Identification of air pollutants of concern

- According to the National Ambient Air Quality Standards, Particulate Matter (PM) 10, 2.5 and SO_2 are common proxy indicators for air pollution.



Artificial Intelligence (AI_r) and the Internet of things (IoT) workflow

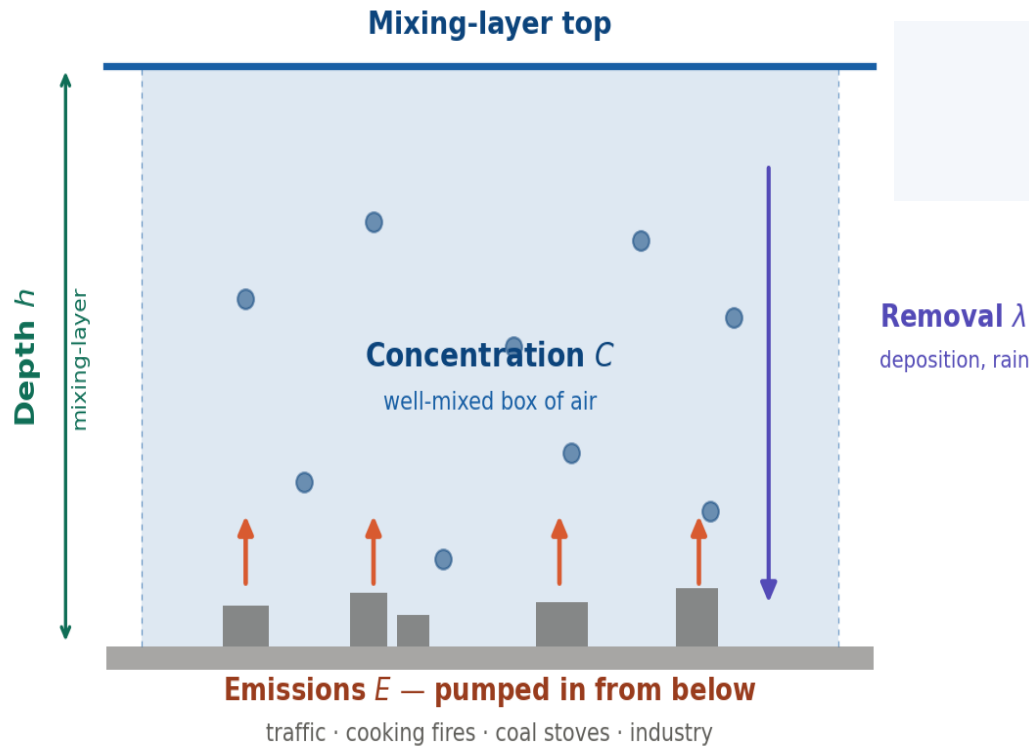
- The **South African Consortium of air quality monitoring** is envisioned to address shortcomings in currently available commercial systems.



Part 2 — The physics, before the predictive model(LSTM)

A boundary-layer budget, and what it dictates

The governing equation: the boundary-layer box model



For emission flux E mixed into a layer of depth h , with loss rate λ and background C_0 :

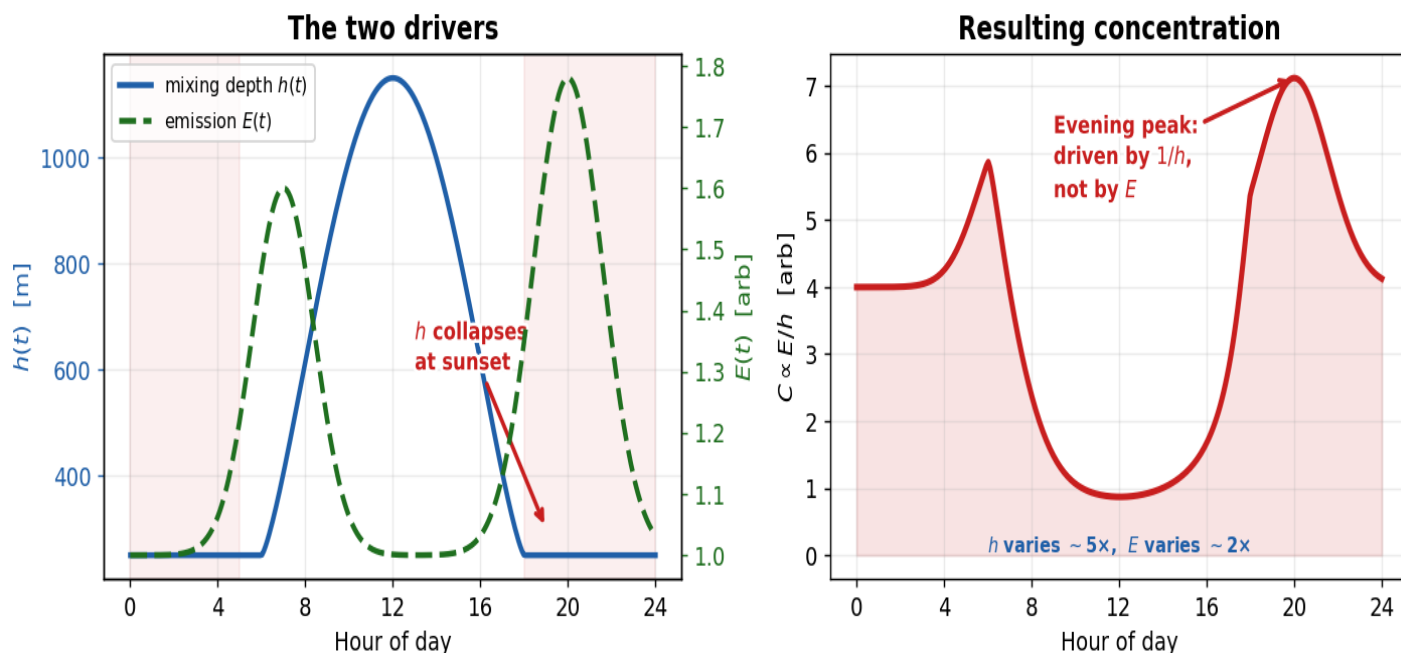
$$\frac{dC}{dt} = \frac{E}{h} - \left(\lambda + \frac{1}{h} \left(\frac{dh}{dt} \right)_+ \right) (C - C_0)$$

The key term is $\frac{E}{h}$:

- concentration is inversely proportional to mixing depth
- collapse $h \Rightarrow$ same mass in a smaller volume $\Rightarrow C$ rises

What really drives the concentration? (Not emissions)

Box model: variance in C is dominated by the meteorological denominator $h(t)$



Over a day, h swings $\sim 5\times$ while emissions vary only $\sim 2\text{--}3\times$.

A model trained only on past $PM_{2.5}$ sees the symptom, not the driver — the mixing-layer height h .

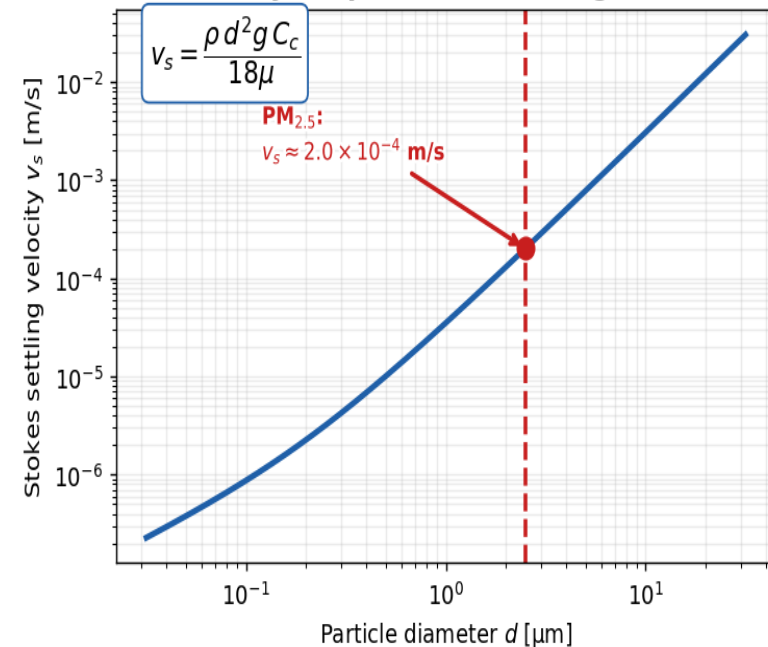
Over a single day the mixing depth varies by a **factor of five**, driven by:

- daytime thermal convection (deep mixing)
- night-time decay of turbulent mixing

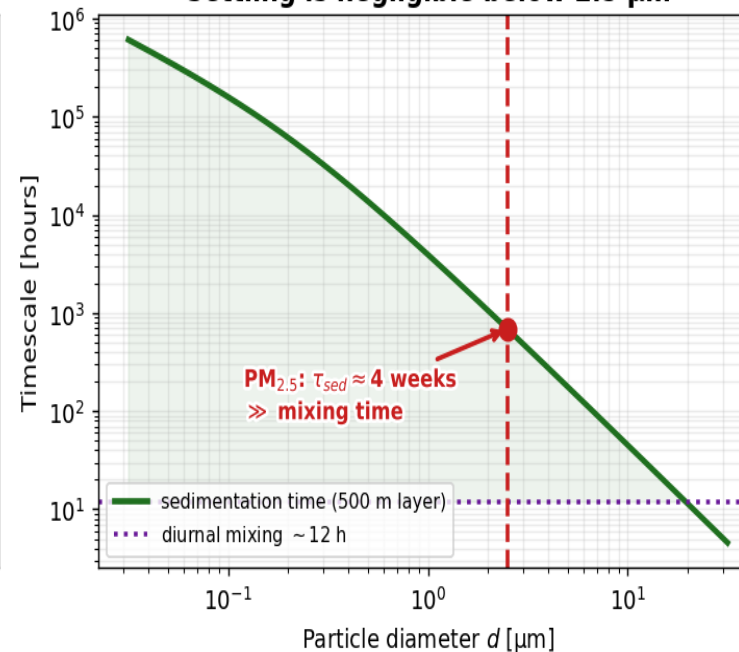
[INTERPRETATION] Variance in C is dominated by the meteorological **denominator** — not an emission at all.

Why “2.5” is interesting physics, and why we can ignore the loss term

Why 2.5 μm : the d^2 settling law



Settling is negligible below 2.5 μm



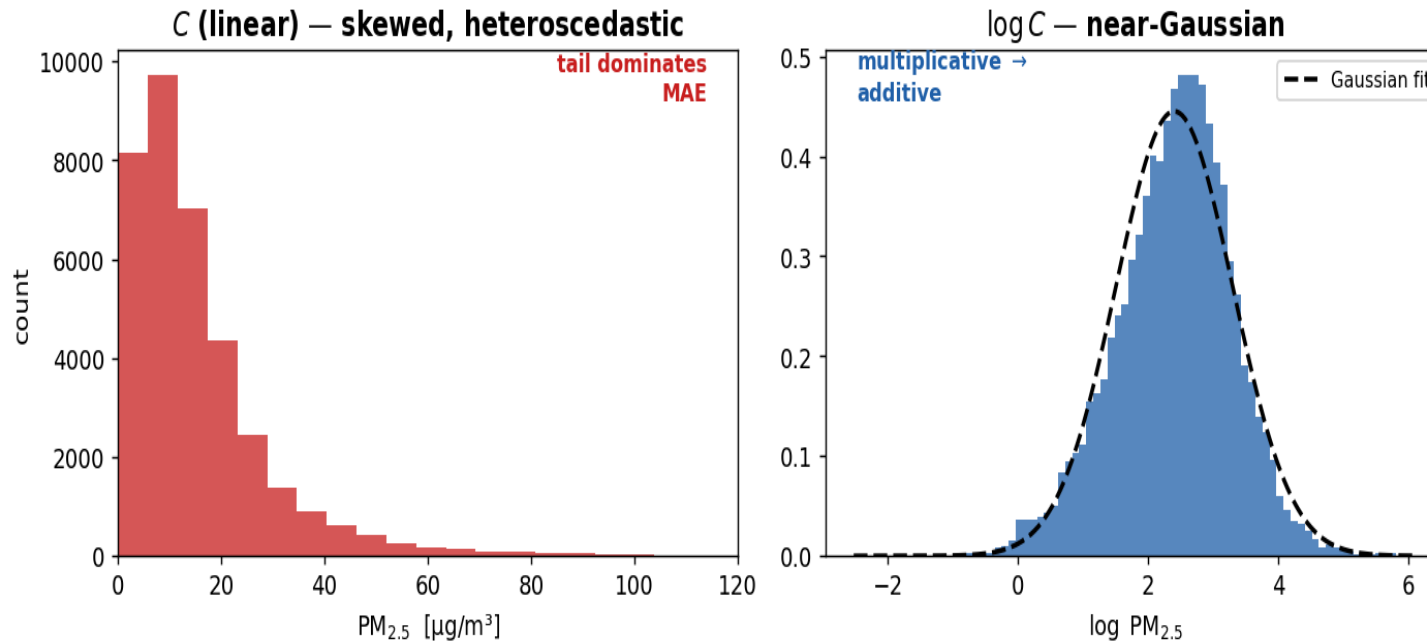
A small sphere falling through air reaches a terminal speed (Stokes' law):

$$v_s = \frac{\rho d^2 g}{18\mu}$$

- at $d = 2.5 \mu\text{m}$: $v_s \approx 2 \times 10^{-4} \text{ m/s}$
- settling time $\approx 4 \text{ weeks}$ (500 m layer)
- mixing time $\approx 12 \text{ h}$ — $\sim 600\times$ faster

Dropping λ is justified. Below $2.5 \mu\text{m}$ the particle is a quasi-passive tracer of the air itself.

C is not the natural variable — its logarithm is

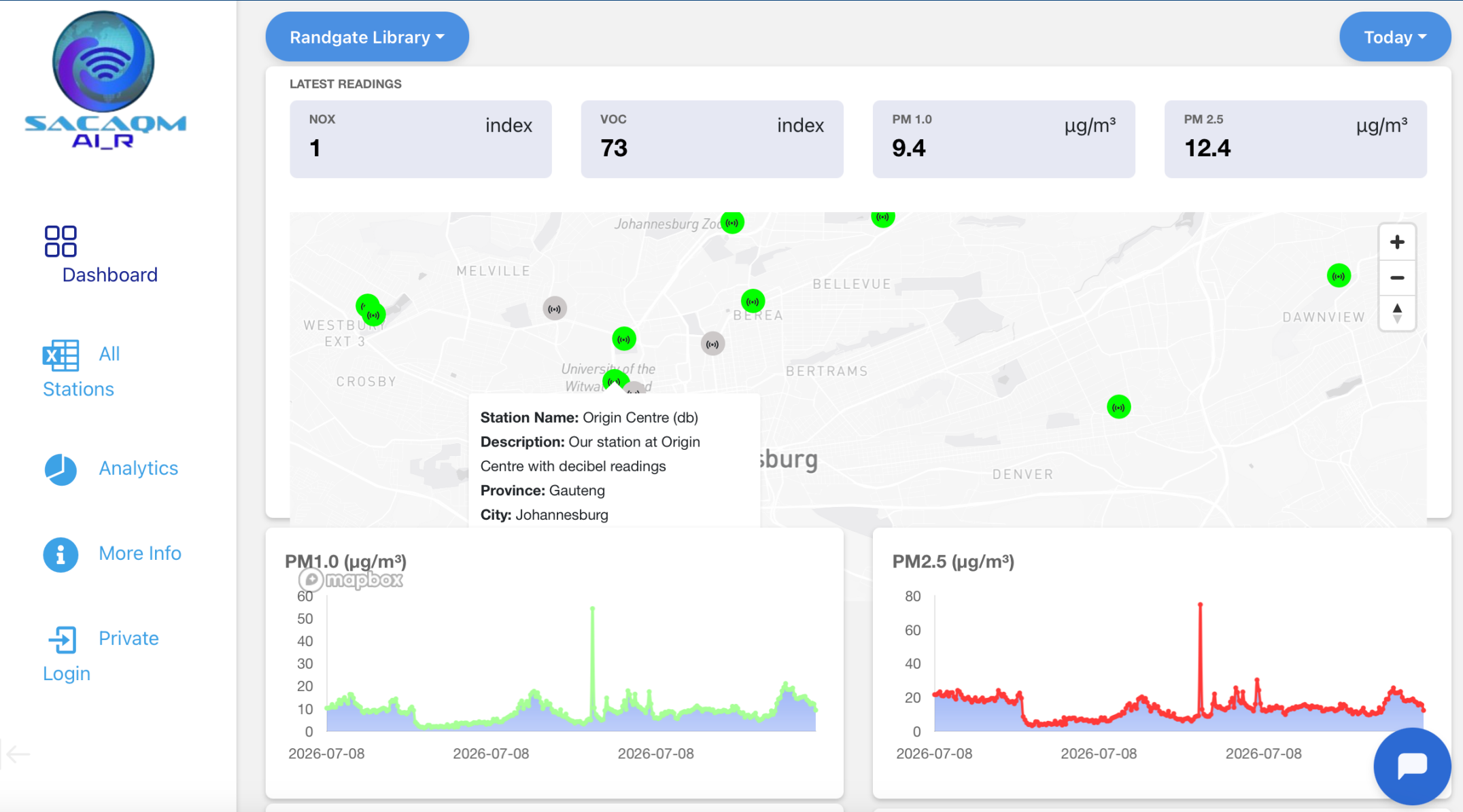


$$C \sim \frac{E}{h} \text{ combines by multiplication, not addition: halve } h \Rightarrow \text{double } C.$$

Many independent factors multiplying together give a log-normal distribution (central limit theorem in log-space).

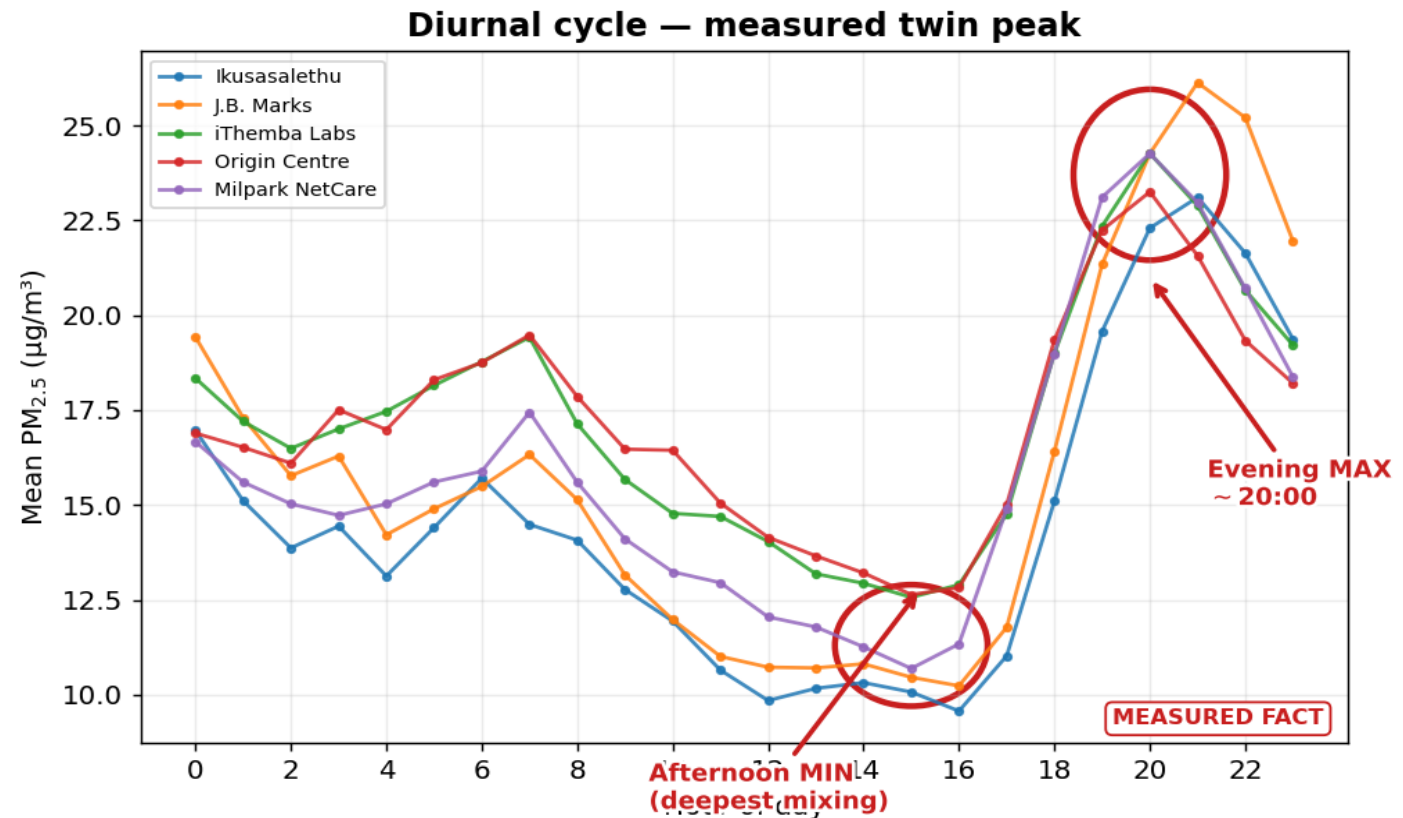
Predict the logarithm of PM_{2.5}, not PM_{2.5} itself.

Part 3 — The data as evidence (Five Gauteng Sensors)

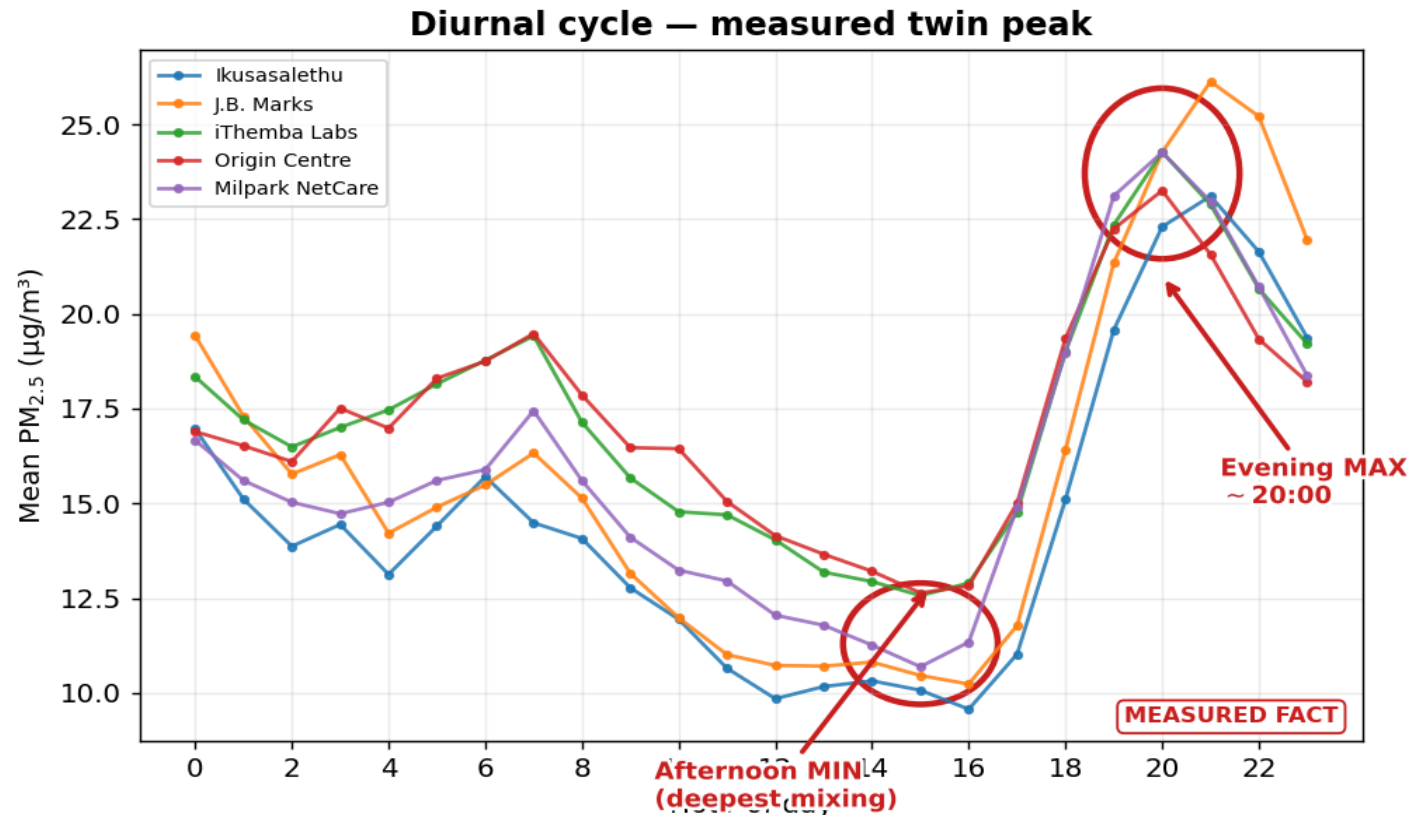


The daily cycle — raw measurement

- Ikusasaletu (Residential)
- J.B Marks (Residential)
- IThemba labs (Research Facility)
- Origin Centre (University)
- Milpark NetCare(Hospital)



The twin-peak daily cycle



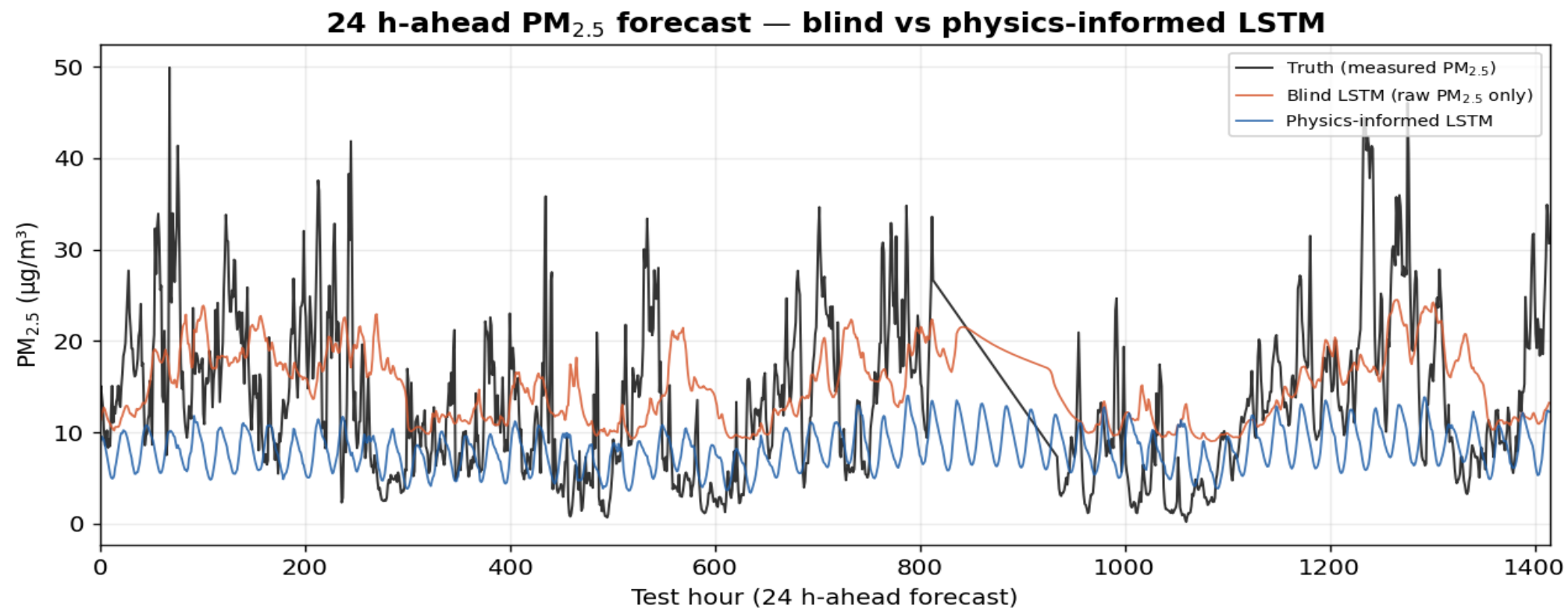
Afternoon minimum (~15:00, deep mixing) and evening maximum (~20:00), at all five stations.

The concentration peak *lags* the emission activity — the tell-tale fingerprint that mixing depth, not emission timing, is the driver.

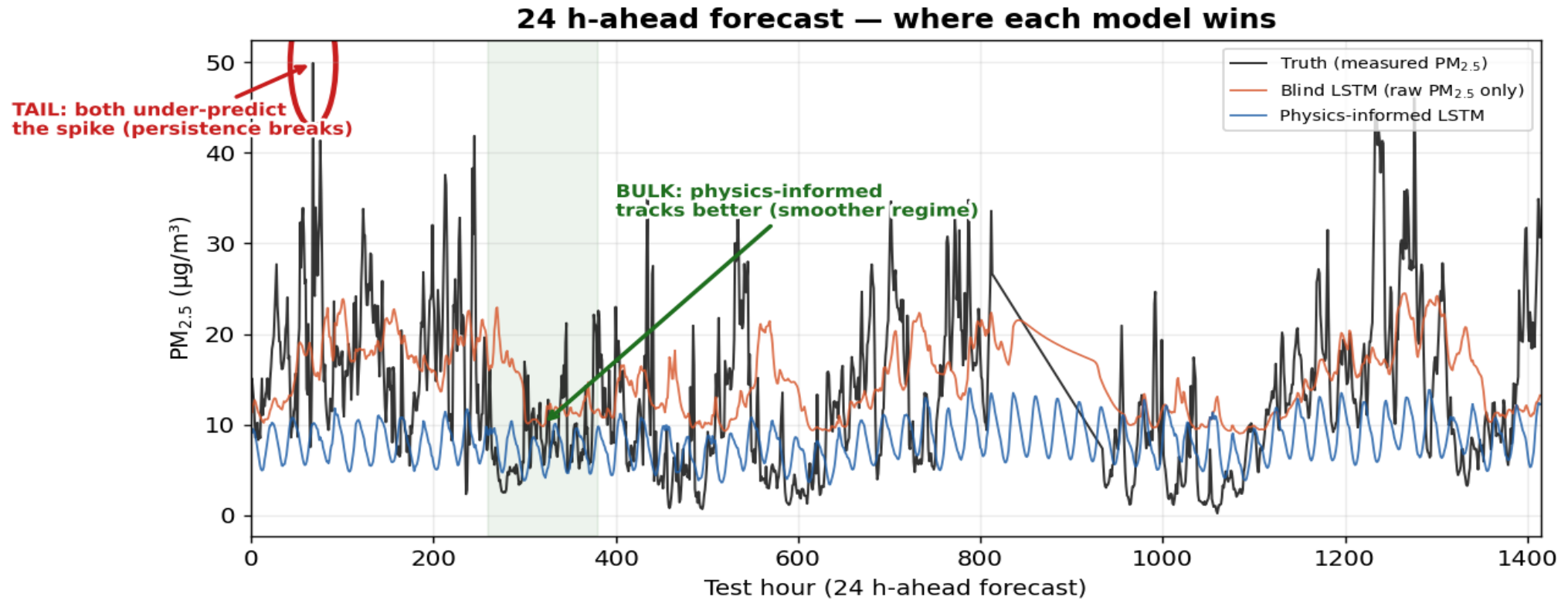
Part 4 — The test (Results)

Blind vs “physics-informed” LSTM

The forecast

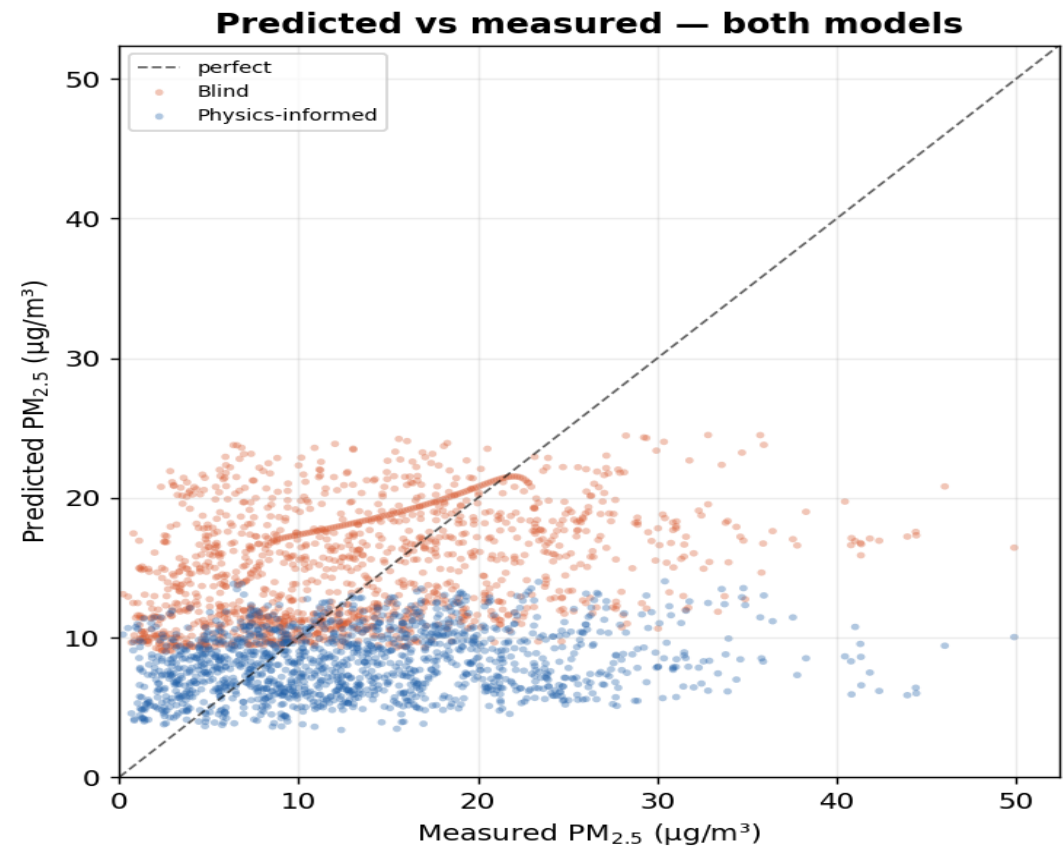


The forecast — where each model wins

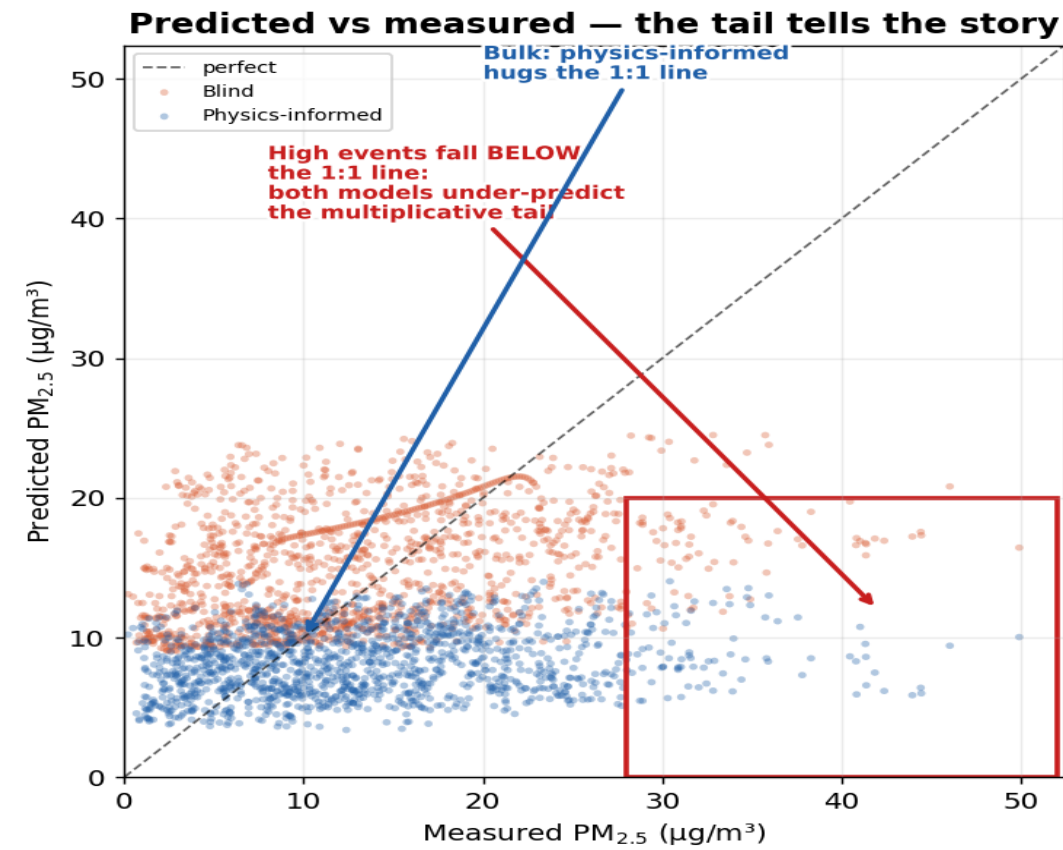


In the **bulk**, the physics-informed model tracks better. On the **tail spike**, both under-predict — persistence alone cannot anticipate the event.

Predicted vs measured



Raw scatter.



Annotated.

Summary

- Where that absorption is possible (bulk, single site) $\Rightarrow$ the two tie.
- Where it is not (the multiplicative tail) $\Rightarrow$ both fail, and the log-target's behaviour is itself a physical prediction of why.
- The physics does not merely improve a model, it explains when a model can work at all, and why it breaks.

Future outlook

- Use Spatial Temporal Graphical Neural Networks as the predictive model

Thank you

Questions?

